

# Chapter 7: Point Estimation

MATH 450

September 21st, 2017

# Where are we?

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<b>Week 1</b> . . . . .	●	Chapter 1: Descriptive statistics
<b>Week 2</b> . . . . .	●	Chapter 6: Statistics and Sampling Distributions
<b>Week 4</b> . . . . .	●	<b>Chapter 7: Point Estimation</b>
<b>Week 7</b> . . . . .	●	Chapter 8: Confidence Intervals
<b>Week 10</b> . . . . .	●	Chapter 9: Test of Hypothesis
<b>Week 13</b> . . . . .	●	Two-sample inference, ANOVA, regression

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## 7.1 Point estimate

- unbiased estimator
- mean squared error
- bootstrap

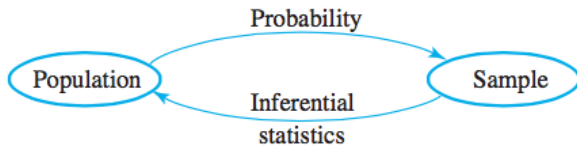
## 7.2 Methods of point estimation

- method of moments
- method of maximum likelihood.

## 7.3 Sufficient statistic

## 7.4 Information and Efficiency

- Large sample properties of the maximum likelihood estimator



## Definition

A point estimate  $\hat{\theta}$  of a parameter  $\theta$  is a single number that can be regarded as a sensible value for  $\theta$ .

population parameter  $\implies$  *sample*  $\implies$  *estimate*  
 $\theta \implies X_1, X_2, \dots, X_n \implies \hat{\theta}$

# Mean Squared Error

- Measuring error of estimation

$$|\hat{\theta} - \theta| \quad \text{or} \quad (\hat{\theta} - \theta)^2$$

- The error of estimation is random

## Definition

The mean squared error of an estimator  $\hat{\theta}$  is

$$E[(\hat{\theta} - \theta)^2]$$

## Theorem

$$MSE(\hat{\theta}) = E[(\hat{\theta} - \theta)^2] = V(\hat{\theta}) + (E(\hat{\theta}) - \theta)^2$$

## Bias-variance decomposition

Mean squared error = variance of estimator + (*bias*)<sup>2</sup>

## Definition

A point estimator  $\hat{\theta}$  is said to be an unbiased estimator of  $\theta$  if

$$E(\hat{\theta}) = \theta$$

for every possible value of  $\theta$ .

Unbiased estimator

$\Leftrightarrow$  Bias = 0

$\Leftrightarrow$  Mean squared error = variance of estimator

## Proposition

*If  $X_1, X_2, \dots, X_n$  is a random sample from a distribution with mean  $\mu$ , then  $\bar{X}$  is an unbiased estimator of  $\mu$ .*

Proof:  $E(\bar{X}) = \mu$ .

- Let

$$T = a_1X_1 + a_2X_2 + \dots + a_nX_n,$$

then the mean and of  $T$  can be computed by

$$E(T) = a_1E(X_1) + a_2E(X_2) + \dots + a_nE(X_n)$$



## Theorem

*The sample variance*

$$S^2 = \frac{1}{n-1} \left[ \left( \sum X_i^2 \right) - \frac{1}{n} \left( \sum X_i \right)^2 \right]$$

*is an unbiased estimator of the population variance  $\sigma^2$ .*

Ideas:

- $V(X) = E[X^2] - (EX)^2$
- $\text{Var}[\bar{X}] = \frac{\sigma^2}{n}$ ,  $E[\bar{X}] = \mu$

# Sample proportion

- A test is done with probability of success  $p$
- $n$  independent tests are done, denote by  $Y$  the number of successes
- Denote by  $X_i$  the result of test  $i^{th}$ , where  $X_i = 1$  when the test success and  $X_i = 0$  if not, then
  - Each  $X_i$  is distributed by

$x$	$0$	$1$
$p(x)$	$1-p$	$p$

- $E[X] = ?$
- Moreover,

$$Y = \sum_{i=1}^n X_i$$

- $E[Y] = ?$

# Sample proportion

- A test is done with probability of success  $p$
- $n$  independent tests are done, denote by  $Y$  the number of successes
- Let

$$\hat{p} = \frac{Y}{n}$$

the  $E[\hat{p}] = p$ , i.e.,  $\hat{p}$  is an unbiased estimator

# Example 1

- A test is done with probability of success  $p$
- $n$  independent tests are done, denote by  $Y$  the number of successes
- Let

$$\hat{p} = \frac{Y}{n}$$

the  $E[\hat{p}] = p$ , i.e.,  $\hat{p}$  is an unbiased estimator

- Crazy idea: How about using

$$\tilde{p} = \frac{Y + 2}{n + 4}$$

- What is the bias of  $\tilde{p}$ ?

## Example 2

### Problem

Suppose a certain type of fertilizer has an expected yield per acre of  $\mu_1$  with variance  $\sigma^2$ , whereas the expected yield for a second type of fertilizer is  $\mu_2$  with the same variance  $\sigma^2$ . Let  $S_1^2$  and  $S_2^2$  denote the sample variances of yields based on sample sizes  $n_1$  and  $n_2$ , respectively, of the two fertilizers.

Show that the pooled (combined) estimator

$$\hat{\sigma}^2 = \frac{(n_1 - 1)S_1^2 + (n_2 - 1)S_2^2}{n_1 + n_2 - 2}$$

is an unbiased estimator of  $\sigma^2$ .

## Example 3

### Problem

Consider a random sample  $X_1, \dots, X_n$  from the pdf

$$f(x) = \frac{1 + \theta x}{2} \quad -1 \leq x \leq 1$$

Show that  $\hat{\theta} = 3\bar{X}$  is an unbiased estimator of  $\theta$ .

## Recap: some properties of variance

- $V(X) = E[(X - EX)^2] = E[X^2] - (EX)^2$
- $V(cX) = c^2V(X)$
- $V(X + c) = V(X)$
- If  $X_1, X_2, \dots, X_n$  are independent, the

$$V(X_1 + X_2 + \dots + X_n) = V(X_1) + V(X_2) + \dots + V(X_n)$$

## Warm-up: Sample proportion

- A test is done with probability of success  $p$
- $n$  independent tests are done, denote by  $Y$  the number of successes
- Denote by  $X_i$  the result of test  $i^{th}$ , where  $X_i = 1$  when the test success and  $X_i = 0$  if not, then
  - Each  $X_i$  is distributed by

$x$	$0$	$1$
$p(x)$	$1-p$	$p$

- $V[X] = ?$
- Moreover,

$$Y = \sum_{i=1}^n X_i$$

- $V[Y] = ?$



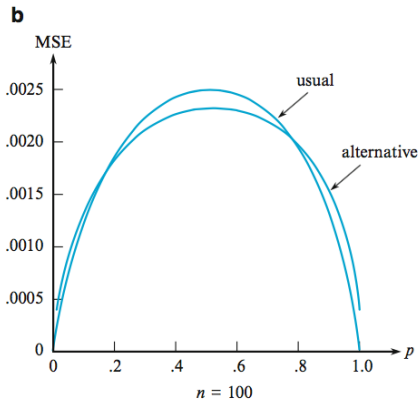
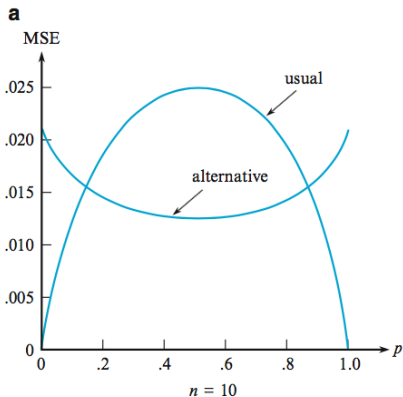
## Example 4

- A test is done with probability of success  $p$
- $n$  independent tests are done, denote by  $Y$  the number of successes
- Crazy idea: How about using

$$\tilde{p} = \frac{Y + \sqrt{n/4}}{n + \sqrt{n}}$$

- What is the bias of  $\tilde{p}$ ?
- Compute  $V(\tilde{p})$ .
- Compute  $\text{MSE}(\tilde{p})$ ?

# Example 7.1 and 7.4



# Minimum variance unbiased estimator (MVUE)

## Definition

Among all estimators of  $\theta$  that are unbiased, choose the one that has minimum variance. The resulting  $\hat{\theta}$  is called the minimum variance unbiased estimator (MVUE) of  $\theta$ .

Recall:

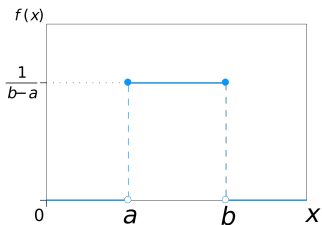
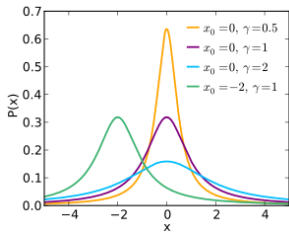
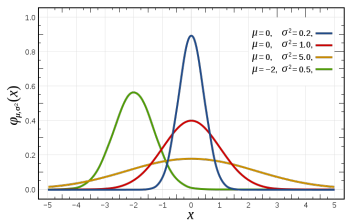
- Mean squared error = variance of estimator +  $(bias)^2$
- unbiased estimator  $\Rightarrow$  bias = 0

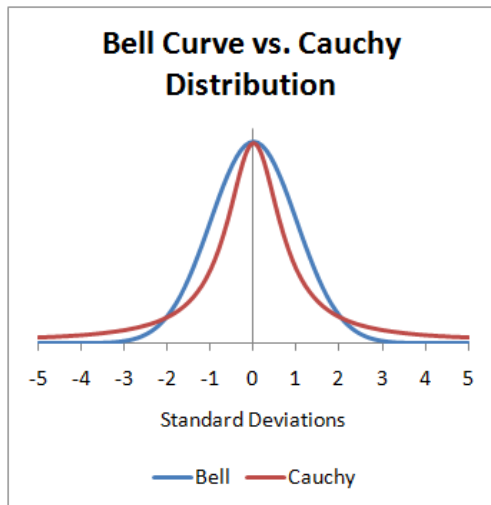
$\Rightarrow$  MVUE has minimum mean squared error among unbiased estimators

## Theorem

*Let  $X_1, \dots, X_n$  be a random sample from a normal distribution with parameters  $\mu$  and  $\sigma$ . Then the estimator  $\hat{\mu} = \bar{X}$  is the MVUE for  $\mu$ .*

# Example 7.8





# What is the best estimator of the mean?

Question: Let  $X_1, \dots, X_n$  be a random sample from a normal distribution with parameters  $\mu$  and  $\sigma$ . What is the best estimator of the mean  $\mu$ ?

Answer: It depends.

- Normal distribution  $\rightarrow$  reasonable tails  $\rightarrow$  sample mean  $\hat{X}$
- Cauchy distribution  $\rightarrow$  heavy tails, symmetric  $\rightarrow$  sample median  $\tilde{X}$
- Uniform distribution  $\rightarrow$  no tails, uniform

$$\hat{X}_e = \frac{\text{largest number} + \text{smaller number}}{2}$$

- In all cases, 10% trimmed mean performs pretty well

# Reporting a point estimate: the standard error

## Definition

$$\text{standard error} = \sigma_{\hat{\theta}} = \sqrt{V(\hat{\theta})}$$

If the standard error itself involves unknown parameters whose values can be estimated, substitution of these estimates into  $\sigma_{\hat{\theta}}$  yields the estimated standard error of the estimator, denoted by  $s_{\hat{\theta}}$ .



# How to compute standard error?

population parameter  $\implies$  *sample*  $\implies$  *estimate*  
 $\theta \implies X_1, X_2, \dots, X_n \implies \hat{\theta}$

- We now that

$$\sigma_{\bar{X}} = \frac{\sigma_X}{\sqrt{n}}$$


- ...but computing that is quite difficult
- What if the formula of  $\hat{\theta}$  is very complicated?

# Parametric model

- Suppose that the population pdf is  $f(x; \theta)$   
(which means that  $X_1, X_2, \dots, X_n$  are sampled from a distribution with pdf  $f(x; \theta)$ )
- data  $x_1, x_2, \dots, x_n$  are collected  $\rightarrow$  point estimate  $\hat{\theta}$
- if we have time/money, we can do the experiment again, collect new set of data, and get  $\hat{\theta}_1$
- do the experiment again, get  $\hat{\theta}_2$
- ...
- do the experiment again for the  $B^{\text{th}}$  time, get  $\hat{\theta}_B$

$$\sigma_{\hat{\theta}} = \sqrt{\frac{1}{B-1} \sum (\hat{\theta}_i - \bar{\theta})^2}, \quad \bar{\theta} = \frac{\hat{\theta}_1 + \hat{\theta}_2 + \dots + \hat{\theta}_B}{B}$$

## boot·strap

*/ˈboʊt,strap/* 

*noun*

1. a loop at the back of a boot, used to pull it on.
2. **COMPUTING**  
a technique of loading a program into a computer by means of a few initial instructions that enable the introduction of the rest of the program from an input device.

*verb*

1. get (oneself or something) into or out of a situation using existing resources.  
"the company is bootstrapping itself out of a marred financial past"
2. **COMPUTING**  
fuller form of **boot**<sup>1</sup> (sense 3 of the verb).

*adjective*

1. (of a person or project) using one's own resources rather than external help.  
"a bootstrap capitalist's trip up the entrepreneurial ladder"

- Suppose that the population pdf is  $f(x; \theta)$   
(which means that  $X_1, X_2, \dots, X_n$  are sampled from a distribution with pdf  $f(x; \theta)$ )
- data  $x_1, x_2, \dots, x_n$  are collected  $\rightarrow$  point estimate  $\hat{\theta}$

Bootstrapping:

- plug  $\hat{\theta}$  into the formula of  $f(x, \theta) \rightarrow$  density function  $f(x, \hat{\theta})$
- *simulate* new sample  $x_1, x_2, \dots, x_n$  from  $f(x, \hat{\theta})$

# Parametric bootstrap

- plug  $\hat{\theta}$  into the formula of  $f(x, \theta)$
- *simulate* new sample  $x_1^*, x_2^*, \dots, x_n^*$  from  $f(x, \hat{\theta})$ 
  - First bootstrap sample:  $x_1^*, x_2^*, \dots, x_n^* \rightarrow \hat{\theta}_1$
  - Second bootstrap sample  $\rightarrow \hat{\theta}_2$
  - $\dots$
  - $B^{\text{th}}$  bootstrap sample  $\rightarrow \hat{\theta}_B$

Bootstrapping estimate:

$$\sigma_{\hat{\theta}} = \sqrt{\frac{1}{B-1} \sum (\hat{\theta}_i - \bar{\theta})^2}, \quad \bar{\theta} = \frac{\hat{\theta}_1 + \hat{\theta}_2 + \dots + \hat{\theta}_B}{B}$$