#### MATH 205: Statistical methods

#### Lecture 8: Basic properties of probability

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#### Announcements

- Homework 1 due this Friday, before lecture
- Quiz 1 this Wednesday (next lecture). Cover materials of Lecture 1–6.

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# Topics

- Sample space and events
- Basic properties of probability
- Advanced properties of probability
- Compute probability
  - Computing event probabilities by counting outcomes

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• Computing probabilities by reasoning about sets

#### Sample space and events

- An experiment: is any action, process, or phenomenon whose outcome is subject to uncertainty
- An outcome: is a result of an experiment Each run of the experiment results in one outcome
- A sample space: is the set of all possible outcomes of an experiment
- An event: is a subset of the sample space.
  An event occurs when one of the outcomes that belong to it occurs

#### Sample space and events: example

- Experiment: Toss a regular dice
- Sample space: {1, 2, 3, 4, 5, 6}
- Some events
  - $E_1$  = the result is an even number = {2, 4, 6}
  - $E_2$  = the result is greater than 2= {3,4,5,6}

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•  $E_3 = \{1, 3, 5, 6\}$ 

### Define probability

- Experiment: Toss two regular dice
- 2  $E_1$  = the summation of the two dice is 11

$$P[E_1] = 1/18$$

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## Different probabilities

- Given an experiment and a sample space, we can define many different probabilities
- Experiment: tossing a coin,  $\Omega = \{H, T\}$
- If you believe the coin is fair:

$$P(\emptyset) = 0, P(\{H\}) = 0.5, P(\{T\}) = 0.5, P(\{H, T\}) = 1.$$

• If you do not, then maybe

 $P(\emptyset) = 0, P({H}) = 0.7, P({T}) = 0.3, P({H, T}) = 1.$ 

## Different views of probability

- Frequentist: The probability of an outcome is the frequency of that outcome in a very large number of repeated experiments
- Bayesian: Probability is a quantification of a belief about how often an outcomes occurs

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## Some fundamental questions

Probability is a function defined on the set of events of an experiment

- 1. What conditions should we impose to define probability?
- 2. How should we adapt probability model with new information?

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#### Basic set operators



Figure 1.1 Venn diagrams of the events specified.

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### What conditions should we impose to define probability?

- P[the sample space] = 1
- $0 \le P[E] \le 1$  for all events E
- $P[\emptyset] = 0$
- If  $E_1$  and  $E_2$  are disjoint then  $P[E_1 \cup E_2] = P[E_1] + P[E_2]$
- If  $E_1$ ,  $E_2$  and  $E_3$  are mutually disjoint then

$$P[E_1 \cup E_2 \cup E_3] = P[E_1] + P[E_2] + P[E_3]$$

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#### Basic properties of probability

Useful Facts 3.1 (Basic Properties of the Probability Events) We have

· The probability of every event is between zero and one; in equations

 $0 \leq P(\mathcal{A}) \leq 1$ 

for any event  $\mathcal{A}$ .

· Every experiment has an outcome; in equations,

 $P(\Omega) = 1.$ 

The probability of disjoint events is additive; writing this in equations requires some notation. Assume that we have a collection of events A<sub>i</sub>, indexed by *i*. We require that these have the property A<sub>i</sub> ∩ A<sub>j</sub> = Ø when *i* ≠ *j*. This means that there is no outcome that appears in more than one A<sub>i</sub>. In turn, if we interpret probability as relative frequency, we must have that

$$P(\cup_i \mathcal{A}_i) = \sum_i P(\mathcal{A}_i)$$

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#### Advanced properties of probability

#### **Useful Facts 3.2 (Properties of the Probability of Events)**

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• 
$$P(\mathcal{A}^c) = 1 - P(\mathcal{A})$$

•  $P(\emptyset) = 0$ 

• 
$$P(\mathcal{A} - \mathcal{B}) = P(\mathcal{A}) - P(\mathcal{A} \cap \mathcal{B})$$

•  $P(\mathcal{A} \cup \mathcal{B}) = P(\mathcal{A}) + P(\mathcal{B}) - P(\mathcal{A} \cap \mathcal{B})$ 

#### Others

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# Problem If $A \subset B$ , then $P(A) \leq P(B)$ .

### Others

#### Problem For any events A, B

$$P(A) = P(A \cap B) + P(A \cap B^{c})$$

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