

Mathematical statistics

March 20th, 2018

Lecture 16: Sufficient statistics and Information

Where are we?

Week 1	●	Probability reviews
Week 2	●	Chapter 6: Statistics and Sampling Distributions
Week 4	●	Chapter 7: Point Estimation
Week 7	●	Chapter 8: Confidence Intervals
Week 10	●	Chapter 9: Test of Hypothesis
Week 14	●	Regression

7.1 Point estimate

- unbiased estimator
- mean squared error

7.2 Methods of point estimation

- method of moments
- method of maximum likelihood.

7.3 Sufficient statistic

7.4 Information and Efficiency

- Large sample properties of the maximum likelihood estimator
- Bootstrap

Sufficient statistic

Definition

A statistic $T = t(X_1, \dots, X_n)$ is said to be sufficient for making inferences about a parameter θ if the joint distribution of X_1, X_2, \dots, X_n given that $T = t$ does not depend upon θ for every possible value t of the statistic T .

Theorem

T is sufficient for θ if and only if nonnegative functions g and h can be found such that

$$f(x_1, x_2, \dots, x_n; \theta) = g(t(x_1, x_2, \dots, x_n), \theta) \cdot h(x_1, x_2, \dots, x_n)$$

i.e. the joint density can be factored into a product such that one factor, h does not depend on θ ; and the other factor, which does depend on θ , depends on x only through $t(x)$.

Example

- Let X_1, X_2, \dots, X_n be a random sample of from a Poisson distribution with parameter λ

$$f(x, \lambda) = \frac{1}{x!} e^{-\lambda x} \quad x = 0, 1, 2, \dots,$$

where λ is unknown.

- Find a sufficient statistic of λ .

Definition

The m statistics $T_1 = t_1(X_1, \dots, X_n)$, $T_2 = t_2(X_1, \dots, X_n)$, \dots , $T_m = t_m(X_1, \dots, X_n)$ are said to be jointly sufficient for the parameters $\theta_1, \theta_2, \dots, \theta_k$ if the joint distribution of X_1, X_2, \dots, X_n given that

$$T_1 = t_1, T_2 = t_2, \dots, T_m = t_m$$

does not depend upon $\theta_1, \theta_2, \dots, \theta_k$ for every possible value t_1, t_2, \dots, t_m of the statistics.

Theorem

T_1, T_2, \dots, T_m are sufficient for $\theta_1, \theta_2, \dots, \theta_k$ if and only if nonnegative functions g and h can be found such that

$$f(x_1, x_2, \dots, x_n; \theta_1, \theta_2, \dots, \theta_k) = g(t_1, t_2, \dots, t_m, \theta_1, \theta_2, \dots, \theta_k) \cdot h(x_1, x_2, \dots, x_n)$$

Example 3

- Let X_1, X_2, \dots, X_n be a random sample from $\mathcal{N}(\mu, \sigma^2)$

$$f_X(x) = \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$$

- Prove that

$$T_1 = X_1 + \dots + X_n, \quad T_2 = X_1^2 + X_2^2 + \dots + X_n^2$$

are jointly sufficient for the two parameters μ and σ .

Example 4

- Let X_1, X_2, \dots, X_n be a random sample from a Gamma distribution

$$f_X(x) = \frac{1}{\Gamma(\alpha)\beta^\alpha} x^{\alpha-1} e^{-x/\beta}$$

where α, β is unknown.

- Prove that

$$T_1 = X_1 + \dots + X_n, \quad T_2 = \prod_{i=1}^n X_i$$

are jointly sufficient for the two parameters α and β .

Information

Definition

The Fisher information $I(\theta)$ in a single observation from a pmf or pdf $f(x; \theta)$ is the variance of the random variable $U = \frac{\partial \log f(X, \theta)}{\partial \theta}$, which is

$$I(\theta) = \text{Var} \left[\frac{\partial \log f(X, \theta)}{\partial \theta} \right]$$

Note: We always have $E[U] = 0$

We have

$$\sum_x f(x, \theta) = 1 \quad \forall \theta$$

Thus

$$\begin{aligned} E[U] &= E \left[\frac{\partial \log f(X, \theta)}{\partial \theta} \right] \\ &= \sum_x \frac{\partial \log f(x, \theta)}{\partial \theta} f(x, \theta) \\ &= \sum_x \frac{\partial f(x, \theta)}{\partial \theta} = 0 \end{aligned}$$

Example

Problem

Let X be distributed by

x	0	1
$f(x, \theta)$	$1 - \theta$	θ

Compute $I(X, \theta)$.

Hint:

- If $x = 1$, then $f(x, \theta) = \theta$. Thus

$$u(x) = \frac{\partial \log f(x, \theta)}{\partial \theta} = \frac{1}{\theta}$$

- How about $x = 0$?

Example

Problem

Let X be distributed by

x	0	1
$f(x, \theta)$	$1 - \theta$	θ

Compute $I(X, \theta)$.

We have

$$\begin{aligned}\text{Var}[U] &= E[U^2] - (E[U])^2 = E[U^2] \\ &= \sum_{x=0,1} U^2(x) f(x, \theta) \\ &= \frac{1}{(1-\theta)^2} \cdot (1-\theta) + \frac{1}{\theta^2} \cdot \theta\end{aligned}$$

The Cramer-Rao Inequality

Theorem

Assume a random sample X_1, X_2, \dots, X_n from the distribution with pmf or pdf $f(x, \theta)$ such that the set of possible values does not depend on θ . If the statistic $T = t(X_1, X_2, \dots, X_n)$ is an unbiased estimator for the parameter θ , then

$$\text{Var}(T) \geq \frac{1}{n \cdot I(\theta)}$$

Proof for $n = 1$

Recall that $E[U] = 0$ and $E[T] = \theta$ (since T is an unbiased estimator of θ) we have

$$\begin{aligned} \text{Cov}(T, U) &= E[TU] - E[U] \cdot E[T] \\ &= \sum_x t(x) \frac{\partial \log f(x, \theta)}{\partial \theta} f(x, \theta) \\ &= \sum_x t(x) \frac{\partial f(x, \theta)}{\partial \theta} \frac{1}{f(x, \theta)} f(x, \theta) \\ &= \frac{\partial}{\partial \theta} \left(\sum_x t(x) f(x, \theta) \right) = 1 \end{aligned}$$

The CauchySchwarz inequality shows that

$$\text{Cov}(T, U) \leq \sqrt{\text{Var}(T) \cdot \text{Var}(U)}$$

which implies

$$\text{Var}(T) \geq \frac{1}{I(\theta)}.$$

Heisenberg's Uncertainty Principle

$$\Delta x \Delta p \geq \frac{h}{4\pi} = \frac{\hbar}{2}$$

↑
uncertainty
in position

↓
uncertainty
in momentum

The more accurately you know the position (i.e., the smaller Δx is), the less accurately you know the momentum (i.e., the larger Δp is); and vice versa

Theorem

Let $T = t(X_1, X_2, \dots, X_n)$ is an unbiased estimator for the parameter θ , the ratio of the lower bound to the variance of T is its efficiency

$$\text{Efficiency} = \frac{1}{nI(\theta)V(T)} \leq 1$$

T is said to be an efficient estimator if T achieves the CramerRao lower bound (i.e., the efficiency is 1).

Note: An efficient estimator is a minimum variance unbiased (MVUE) estimator.

Theorem

Given a random sample X_1, X_2, \dots, X_n from the distribution with pmf or pdf $f(x, \theta)$ such that the set of possible values does not depend on θ . Then for large n the maximum likelihood estimator $\hat{\theta}$ has approximately a normal distribution with mean θ and variance $\frac{1}{n \cdot I(\theta)}$.

More precisely, the limiting distribution of $\sqrt{n}(\hat{\theta} - \theta)$ is normal with mean 0 and variance $1/I(\theta)$.

The Central Limit Theorem

Theorem

Let X_1, X_2, \dots, X_n be a random sample from a distribution with mean μ and variance σ^2 . Then, in the limit when $n \rightarrow \infty$, the standardized version of \bar{X} have the standard normal distribution

$$\lim_{n \rightarrow \infty} \mathbb{P} \left(\frac{\bar{X} - \mu}{\sigma/\sqrt{n}} \leq z \right) = \mathbb{P}[Z \leq z] = \Phi(z)$$