

Mathematical techniques in data science

Lecture 13: Model consistency the lasso estimator

March 18th, 2019

Schedule

Week	Chapter
1	Chapter 2: Intro to statistical learning
3	Chapter 4: Classification
4	Chapter 9: Support vector machine and kernels
5, 6	Chapter 3: Linear regression
7	Chapter 8: Tree-based methods + Random forest
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9	Neural network
12	PCA → Manifold learning
11	Clustering: K-means → Spectral Clustering
10	Bootstrap + Bayesian methods + UQ
13	Reinforcement learning/Online learning/Active learning
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Chapter 3 & 6: Topics on Linear regression

- Linear regression
- Subset selection
- Shrinkage methods
- Model consistency of lasso

Note: Homework 2 is uploaded. Due on 03/29 at 5pm.

- We start with the simple linear regression problem

$$Y = \beta_1 X^{(1)} + \beta_2 X^{(2)} + \epsilon, \quad \epsilon \sim \mathcal{N}(0, \sigma^2)$$

- Sparsity: assume that the data is generated using the “true” vector of parameters $\beta^* = (\beta_1^*, 0)$.
- We assume that $E[X^{(1)}] = E[X^{(2)}] = 0$.

- we observe a dataset $(x_1, y_1), (x_2, y_2), \dots, (x_n, y_n)$
- use the same notations as in the previous lectures

$$\mathbf{Y} = \begin{bmatrix} y_1 \\ y_2 \\ \dots \\ y_n \end{bmatrix} \quad \mathbf{X} = \begin{bmatrix} x_1^{(1)} & x_1^{(2)} \\ \dots & \dots \\ x_n^{(1)} & x_n^{(2)} \end{bmatrix}$$

The lasso estimator solves the optimization problem

$$\hat{\beta} = \min_{\beta} \frac{1}{2} \|\mathbf{Y} - \mathbf{X}\beta\|_2^2 + \lambda(|\beta_1| + |\beta_2|).$$

We want to investigate the conditions under which we can verify that

$$\text{sign}(\hat{\beta}_1) = \text{sign}(\beta_1^*) \quad \text{and} \quad \hat{\beta}_2 = 0$$

Issue: the penalty of lasso is non-differentiable

Definition

We say that a vector $s \in \mathbb{R}^k$ is a subgradient for the ℓ_1 -norm evaluated at $\beta \in \mathbb{R}^k$, written as $s \in \partial\|\beta\|$ if for $i = 1, \dots, k$ we have

$$s_i = \text{sign}(\beta_i) \quad \text{if } \beta_i \neq 0 \quad \text{and } s_i \in [-1, 1] \quad \text{otherwise.}$$

Theorem

- (a) A vector $\hat{\beta}$ solve the lasso program if and only if there exists a $\hat{z} \in \partial\|\hat{\beta}\|$ such that

$$X^T(Y - X\hat{\beta}) - \lambda\hat{z} = 0 \quad (0.1)$$

- (b) Suppose that the subgradient vector satisfies the strict dual feasibility condition

$$|\hat{z}_2| < 1$$

then **any** lasso solution $\tilde{\beta}$ satisfies $\tilde{\beta}_2 = 0$.

- (c) Under the condition of part (b), if $X^{(1)} \neq 0$, then $\hat{\beta}$ is the unique lasso solution.

The primal-dual witness method.

The primal-dual witness (PDW) method consists of constructing a pair of $(\tilde{\beta}, \tilde{z})$ according to the following steps:

- First, we obtain $\tilde{\beta}_1$ by solving the restricted lasso problem

$$\tilde{\beta}_1 = \min_{\beta=(\beta_1,0)} \frac{1}{2} \|\mathbf{Y} - \mathbf{X}\beta\|_2^2 + \lambda(|\beta_1|).$$

Choose a subgradient $\tilde{z}_1 \in \mathbb{R}$ for the ℓ_1 -norm evaluated at $\tilde{\beta}_1$

- Second, we solve for a vector \tilde{z}_2 satisfying equation (0.1), and check whether or not the dual feasibility condition $|\tilde{z}_2| < 1$ is satisfied
- Third, we check whether the *sign consistency condition*

$$\tilde{z}_1 = \text{sign}(\beta_1^*)$$

is satisfied.

- This procedure is not a practical method for solving the ℓ_1 -regularized optimization problem, since solving the restricted problem in Step 1 requires knowledge about the sparsity of β^*
- Rather, the utility of this constructive procedure is as a proof technique: it succeeds if and only if the lasso has a optimal solution with the correct signed support.

A more detailed computation

We note that the matrix form of equation (0.1) can be written as

$$[X^{(1)}]^T(Y - X^{(1)}\beta_1 - X^{(2)}\beta_2) - \lambda\hat{z}_1 = 0$$

$$[X^{(2)}]^T(Y - X^{(1)}\beta_1 - X^{(2)}\beta_2) - \lambda\hat{z}_2 = 0$$

To simplify the notation, we denote

$$C_{ij} = [X^{(i)}]^T[X^{(j)}]$$

- we find $\tilde{\beta}_1$ and \tilde{z}_1 that satisfies

$$[X^{(1)}]^T(Y - X^{(1)}\tilde{\beta}_1) - \lambda\tilde{z}_1 = 0$$

- Moreover, to make sure that the sign consistency in Step 3 is satisfied, we impose that

$$\tilde{z}_1 = \text{sign}(\beta_1^*) \quad \text{and} \quad \tilde{\beta}_1 = C_{11}^{-1}([X^{(1)}]^T Y - \lambda \text{sign}(\beta_1^*)).$$

This is acceptable as long as $\tilde{z}_1 \in \partial|\tilde{\beta}_1|$. That is,

$$\text{sign}(\tilde{\beta}_1) = \text{sign}(\beta_1^*)$$

- Step 2:

$$[X^{(2)}]^T(Y - X^{(1)}\tilde{\beta}_1) - \lambda\hat{z}_2 = 0$$

- Choose

$$\tilde{z}_2 = \frac{1}{\lambda}[X^{(2)}]^T(Y - X^{(1)}\tilde{\beta}_1).$$

We want $|\tilde{z}_2| < 1$.

In principle, we want two conditions:

- $\text{sign}(\tilde{\beta}_1) = \text{sign}(\beta_1^*)$
- $|\tilde{z}_2| < 1$

Recalling that $Y = X^{(1)}\beta_1^* + \epsilon$, we have

$$\begin{aligned}\tilde{\beta}_1 &= C_{11}^{-1}([X^{(1)}]^T (X^{(1)}\beta_1^* + \epsilon) - \lambda \text{sign}(\beta_1^*)) \\ &= \beta_1^* + C_{11}^{-1}([X^{(1)}]^T \epsilon - \lambda \text{sign}(\beta_1^*))\end{aligned}$$

Thus if we denote

$$\Delta = C_{11}^{-1}([X^{(1)}]^T \epsilon - \lambda \text{sign}(\beta_1^*))$$

then the first condition can be further simplified as $\text{sign}(\beta_1^*) = \text{sign}(\beta_1^* + \Delta)$.

Similarly,

$$\begin{aligned} \tilde{z}_2 &= \frac{1}{\lambda} [X^{(2)}]^T (X^{(1)} \beta_1^* + \epsilon - X^{(1)} \tilde{\beta}_1) \\ &= \frac{1}{\lambda} [X^{(2)}]^T (X^{(1)} \Delta + \epsilon) \end{aligned}$$

- we assume that the observations are collected with no noise ($\epsilon = 0$).
- Then

$$\Delta = -C_{11}^{-1} \lambda \text{sign}(\beta_1^*)$$

and

$$\tilde{z}_2 = \frac{-1}{\lambda} C_{21} \Delta = C_{21} C_{11}^{-1} \text{sign}(\beta_1^*)$$

- Mutual incoherence: $|C_{21} C_{11}^{-1}| < 1$.
- Minimum signal: $|\beta_1^*| > \lambda C_{11}^{-1}$