

Mathematical techniques in data science

Lecture 35: t-SNE and Laplace Eigenmap

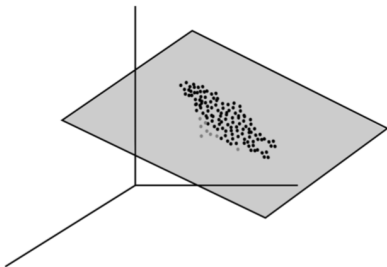
Admins

- There will be no Homework 5
- Project presentations:
 - Wed 05/11
 - Fri 05/13
 - Mon 05/16
- Project report due: Thu 05/19

Topics

- Linear methods
 - Principal component analysis
 - Multi-dimensional scaling (MDS)
- Non linear methods
 - Isomap
 - Locally linear embedding (LLE)
 - t -distributed Stochastic Neighbor Embedding (t -SNE)
 - Spectral embedding (Laplace Eigenmap)

Principal component analysis



Problem: How can we discover low dimensional structures in data?

- Principal components analysis: construct projections of the data that capture most of the *variability* in the data.
- Provides a low-rank approximation to the data.
- Can lead to a significant dimensionality reduction.

Multidimensional scaling: preserve distance

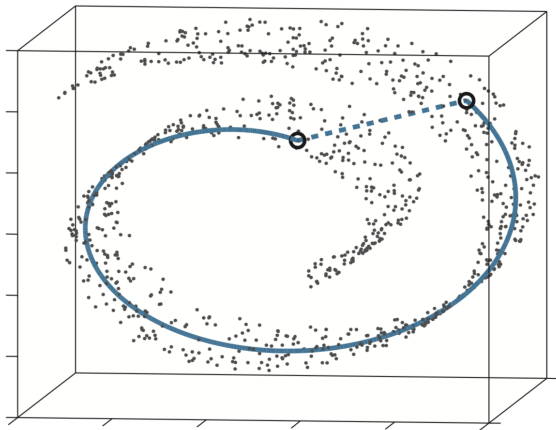
- The data to be analyzed is a collection of n objects on which a distance function is defined: d_{ij} is the distance between objects i and object j
- Given d_{ij} , MDS want to finds vector $z_1, z_2, \dots, z_n \in \mathbb{R}^d$ such that

$$d_{ij} \approx \|z_i - z_j\|$$

- MDS is formulated as an optimization problem

$$\min_{z_1, \dots, z_n} \sum_{i < j} (d_{ij} - \|z_i - z_j\|)^2$$

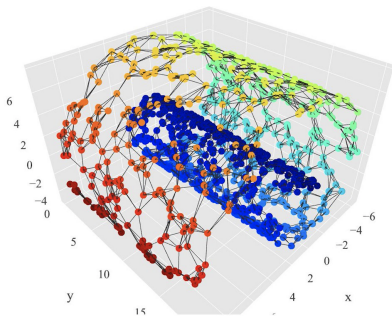
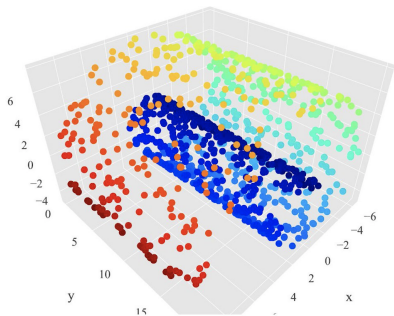
Distance on a manifold

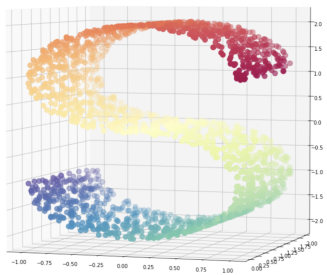


Isomap: preserve intrinsic distance

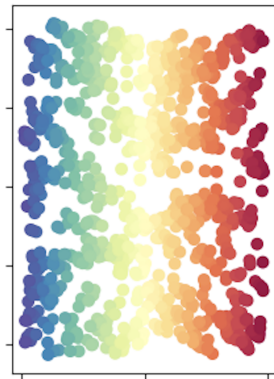
- Compute intrinsic distance
 - For each point, determine the neighbours
 - K nearest neighbors
 - all points in a fixed radius
 - Construct a neighborhood graph
 - each point is connected to its neighbors
 - edge length equal to Euclidean distance between the points
 - Compute shortest paths between two nodes
- Lower-dimensional embedding using MDS

Neighbor graph





Isomap (0.34 sec)



Locally linear embedding: preserve local linear structure

1. For each data point x_i in p dimensions, we find its K -nearest neighbors $\mathcal{N}(i)$ in Euclidean distance.
2. We approximate each point by an affine mixture of the points in its neighborhood:

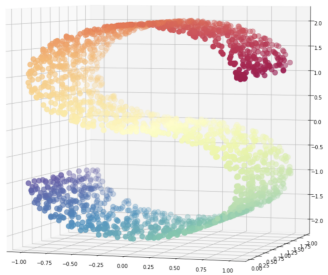
$$\min_{W_{ik}} \|x_i - \sum_{k \in \mathcal{N}(i)} w_{ik} x_k\|^2 \quad (14.102)$$

over weights w_{ik} satisfying $w_{ik} = 0$, $k \notin \mathcal{N}(i)$, $\sum_{k=1}^N w_{ik} = 1$. w_{ik} is the contribution of point k to the reconstruction of point i . Note that for a hope of a unique solution, we must have $K < p$.

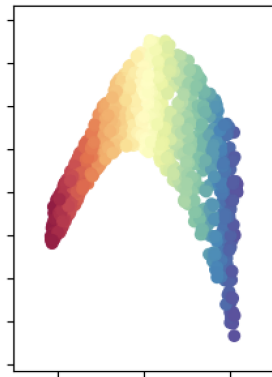
3. Finally, we find points y_i in a space of dimension $d < p$ to minimize

$$\sum_{i=1}^N \|y_i - \sum_{k=1}^N w_{ik} y_k\|^2 \quad (14.103)$$

with w_{ik} fixed.



LLE (0.11 sec)



t-distributed stochastic neighbor embedding

t-SNE

- All methods proposed so far are great, and they work well if \mathcal{M} is a manifold of low-dimension (2 dimension)
- Sometimes, even if the dimension of \mathcal{M} is high, we still want to embed it to \mathbb{R}^2 for learning

t-SNE

- There are many problems with embedding high-dimensional manifold to low-dimensional space
- Structural differences
 - in ten dimensions, it is possible to have 11 data points that are mutually equidistant
 - there is no way to model this faithfully in a two-dimensional map
- Crowding problem:
 - the volume of a sphere centered on datapoint i scales as r^m , where r is the radius and m the dimensionality of the sphere
 - the area of the two-dimensional map that is available to accommodate moderately distant data points will not be nearly large enough compared with the area available to accommodate nearby data points

Stochastic neighbor embedding

- converting the high-dimensional Euclidean distances between data points into conditional probabilities that represent similarities
- The similarity of datapoint x_j to datapoint x_i is the conditional probability, $p_{j|i}$, that x_i would pick x_j as its neighbor if neighbors were picked in proportion to their probability density under a Gaussian centered at x_i

$$p_{ij} = \frac{\exp(-\|x_i - x_j\|^2 / 2\sigma^2)}{\sum_{k \neq i} \exp(-\|x_k - x_i\|^2 / 2\sigma^2)}$$

Stochastic neighbor embedding

- Assume that the data points are mapped to y_1, y_2, \dots, y_n in low-dimension
- we construct a similar quantity for a y

$$q_{ij} = \frac{\exp(-\|y_i - y_j\|^2)}{\sum_{k \neq l} \exp(-\|y_k - y_l\|^2)}$$

- Goal: Minimize the difference between the two probabilities

$$\min_y \sum_i \sum_j p_{ij} \log \frac{p_{ij}}{q_{ij}}$$

t-SNE

- employ a Student t-distribution with one degree of freedom (which is the same as a Cauchy distribution) as the heavy-tailed distribution in the low-dimensional map

$$q_{ij} = \frac{(1 + \|y_i - y_j\|^2)^{-1}}{\sum_{k \neq l} (1 + \|y_k - y_l\|^2)^{-1}}$$

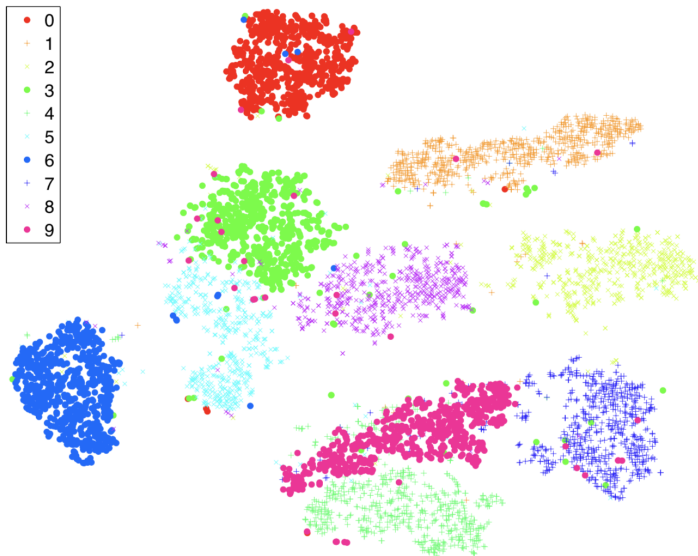
- Goal: Minimize the difference between the two probabilities

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Visualization of MNIST by Isomap



Visualization of MNIST by t-SNE



Laplace eigenmap

The Laplace-Beltrami operator

- Let \mathcal{M} be a manifold. We look for a map from the manifold such that points close together on the manifold are mapped close together
- Locally, we have

$$f(z) - f(x) \approx \langle \nabla f(x), z - x \rangle$$

and $\|\nabla f(x)\|$ is a measure of local distortion by the map

- Idea:

$$\min_{\|f\|_{L_2(\mathcal{M})}=1} \int_{\mathcal{M}} \|\nabla f\|^2$$

The Laplace-Beltrami operator

- Idea:

$$\min_{\|f\|_{L_2(\mathcal{M})}=1} \int_{\mathcal{M}} \|\nabla f\|^2$$

- Define

$$\mathcal{L}(f) = -\operatorname{div} \nabla f$$

then

$$\int_{\mathcal{M}} \|\nabla f\|^2 = \int_{\mathcal{M}} \mathcal{L}(f)f$$

The Laplace-Beltrami operator

- We have

$$\int_{\mathcal{M}} \|\nabla f\|^2 = \int_{\mathcal{M}} \mathcal{L}(f)f = \langle \mathcal{L}(f), f \rangle$$

- Problem: in manifold learning, we don't have information about the manifold, just a sample of it
- Question: how to approximate $\mathcal{L}(f)$ by the samples?

Heat kernel

In \mathbb{R}^m , we know that the heat equation

$$\begin{aligned}u_t(x, t) - \mathcal{L}u(x, t) &= 0 \\ u(x, 0) &= f(x)\end{aligned}$$

has solution of the form

$$u(x, t) = \int H_t(x, y) f(y) dy$$

with

$$H_t(x, y) \approx (4\pi t)^{-m/2} e^{-\frac{|x-y|^2}{4t}}$$

when $t \approx 0$ and $x \approx y$, and

$$\lim_{t \rightarrow 0} \int H_t(x, y) f(y) dy = f(x)$$

Heat kernel

- We deduce that

$$\begin{aligned}\mathcal{L}f(x) &= \mathcal{L}f u(x, 0) = -u_t(x, t)|_{t=0} \\ &\approx \frac{1}{t} \left[f(x) - (4\pi t)^{-m/2} \int e^{-\frac{|x-y|^2}{4t}} f(y) \right]\end{aligned}$$

- Sketchy maths
 - locally, \mathcal{M} are just Euclidean space, and heat are transferred in a very similar way
 - If t is small, long term interaction on the manifold are killed
 - Laplace of a constant function is 0

Approximating the Laplace operator

$$\mathcal{L}f(x) \approx \frac{1}{t} \left[f(x) - (4\pi t)^{-m/2} \int e^{-\frac{|x-y|^2}{4t}} f(y) \right]$$

- Sketchy maths
 - locally, \mathcal{M} are just Euclidean space, and heat are transferred in a very similar way
 - If t is small, long term interactions on the manifold are killed
 - Laplace of a constant function is 0
- Then $\mathcal{L}f(x_i)$ can be approximate by

$$C \left[f(x_i) \sum_{0 < |x_i - x_j| < \epsilon} e^{-\frac{|x_i - x_j|^2}{4t}} - \sum_{0 < |x_i - x_j| < \epsilon} e^{-\frac{|x_i - x_j|^2}{4t}} f(x_j) \right]$$

Approximating the Laplace operator

- $\mathcal{L}f(x_i)$ can be approximate by

$$C \left[f(x_i) \sum_{0 < |x_i - x_j| < \epsilon} e^{-\frac{|x_i - x_j|^2}{4t}} - \sum_{0 < |x_i - x_j| < \epsilon} e^{-\frac{|x_i - x_j|^2}{4t}} f(x_j) \right]$$

- Denote

$$W_{ij} = e^{-\frac{|x_i - x_j|^2}{4t}}, \quad |x_i - x_j| < \epsilon$$

and D is the diagonal matrix with entry $D_{ii} = \sum_j W_{ij}$

- We want to find f such that

$$\langle (D - W)f, f \rangle$$

is minimized

Laplace eigenmap

Step 1: Construct the neighbor graph

- For each point, determine either
 - K nearest neighbors
 - all points in a fixed radius
- each point is connected to its neighbours
- edge length equal to ~~Euclidean distance between the points~~

$$W_{ij} = e^{-\frac{|x_i - x_j|^2}{4t}}$$

Laplace eigenmap

Step 2: Embedding by Laplace operator's eigenvectors

- Define $L = D - W$
- We want to minimize

$$\min_{\langle Df, f \rangle = 1} \langle Lf, f \rangle$$

- Solve for eigenvectors $\{f_1, f_2, \dots, f_m\}$
- Map

$$x \rightarrow (\langle f_1, x \rangle, \langle f_2, x \rangle, \dots, \langle f_m, x \rangle)$$